



# Intelligent Infrared Carbon Dioxide Module (Model: MH-Z14)

## User's Manual V2.4

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Zhengzhou Winsen Electronics Technology CO., LTD.

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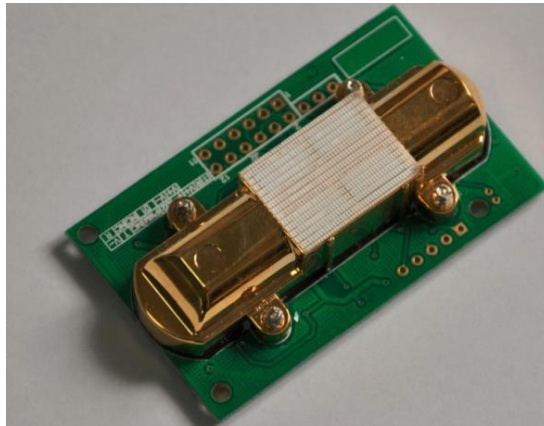
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Please keep the manual properly, in order to get help if you have questions during the usage in the future.

Zhengzhou Winsen Electronics Technology CO., LTD

# MH-Z14 NDIR CO2 Module

## 1. Profile



MH-Z14 NDIR Infrared gas module is a common type, small size sensor, using non-dispersive infrared (NDIR) principle to detect the existence of CO<sub>2</sub> in the air, with good selectivity, non-oxygen dependent and long life. Built-in temperature sensor can do temperature compensation; and it has digital output and analog voltage output. This common type infrared gas sensor is developed by the tight integration of mature infrared absorbing gas detection technology, Precision optical circuit design and superior circuit design.

Its design, production and inspection adhere to below: *GB/T13384-92*

## 2. Applications:

MH-Z14 NDIR Infrared gas module is applied in the HVAC, indoor air quality monitoring, industrial process, safety and protection monitoring, agriculture and animal husbandry production process monitoring.

## 3. Main functions and features :

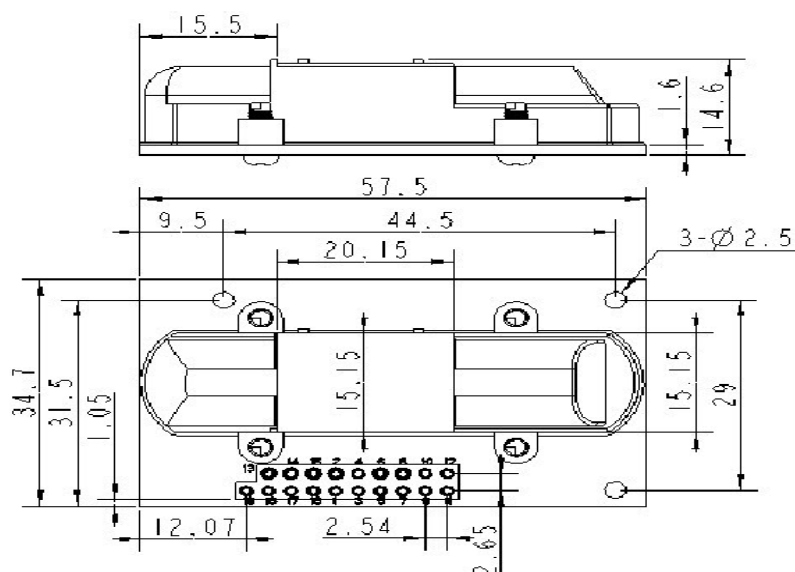
- High sensitivity, High resolution
- Low power consumption
- Output modes: UART, analog voltage signal, PWM wave
- Quick response
- Temperature compensation, excellent linear output
- Good stability
- Long lifespan
- Anti-water vapor interference
- No poisoning

## 4. Main technical parameters

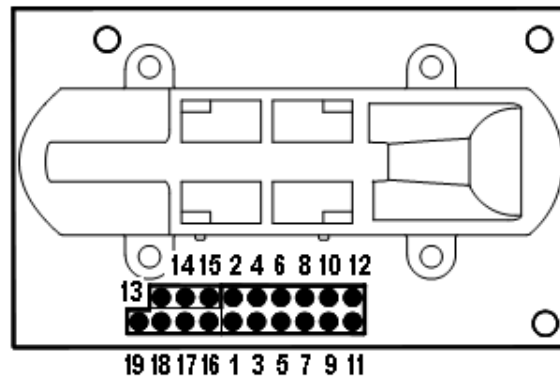
|                     |                        |
|---------------------|------------------------|
| Working voltage     | 4.5 V ~ 5.5V DC        |
| Average current     | < 85 mA                |
| Interface level     | 3.3 V                  |
| Measuring range     | 0~5%VOL optional       |
| Output signal       | PWM                    |
|                     | UART                   |
|                     | 0.4-2V DC              |
| Preheat time        | 3min                   |
| Response Time       | $T_{90} < 90s$         |
| Working temperature | 0°C ~ 50°C             |
| Working humidity    | 0~95%RH                |
| Weight              | 15 g                   |
| Lifespan            | >5 year                |
| Dimension           | 57.5×34.7×16mm (L×W×H) |

| Target Gas                           | Measuring Range | Accuracy                        | Mark                        |
|--------------------------------------|-----------------|---------------------------------|-----------------------------|
| Carbon Dioxide<br>(CO <sub>2</sub> ) | 0~2000ppm       | ±(50ppm<br>+5%reading<br>value) | Temperature<br>compensation |
|                                      | 0~5000ppm       |                                 | Temperature<br>compensation |
|                                      | 0~1%VOL         |                                 | Temperature<br>compensation |
|                                      | 0~5%VOL         |                                 | Temperature<br>compensation |

## 5. Structure

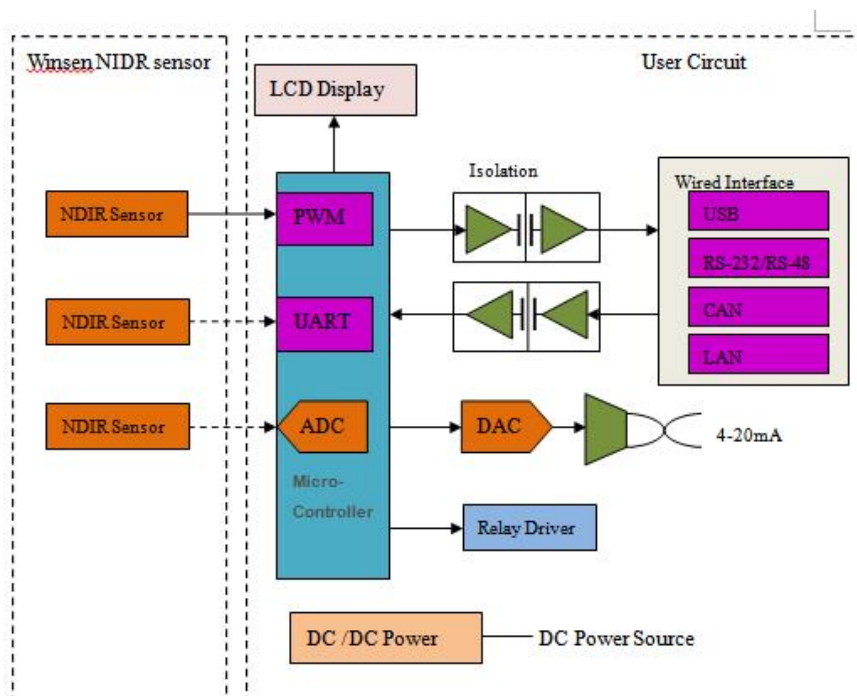


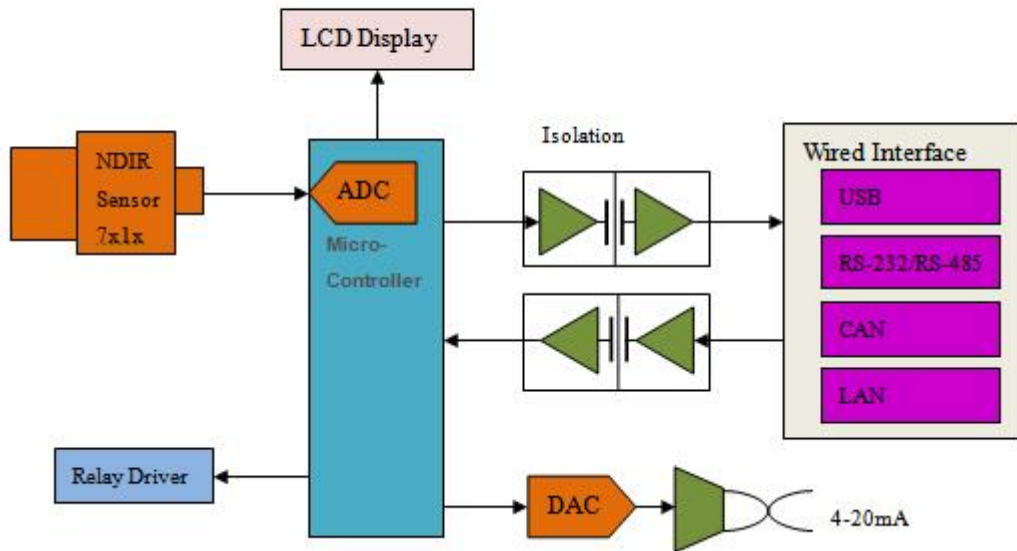
## 6. Definition for pins



| PIN                    | Description                      |
|------------------------|----------------------------------|
| Pad1/Pad15/Pad17       | Vin (input voltage 4.5V~5.5V)    |
| Pad2/Pad3/ Pad12/Pad16 | GND                              |
| Pad4                   | Vout2 (0.4~2V)                   |
| Pad5                   | Vout1 (0~2.5V)                   |
| Pad6                   | PWM                              |
| Pad8                   | HD                               |
| Pad7/Pad9              | NC                               |
| Pad11/Pad14/Pad18      | UART (RXD) 0~3.3V input digital  |
| Pad10/Pad13/Pad19      | UART (TXD) 0~3.3V output digital |

## 7. Circuit





## 8. Operating instruction

### 8.1 Analog output connections

The output value of Vout1 is 0-2.5V, which stands for 0 to full range.

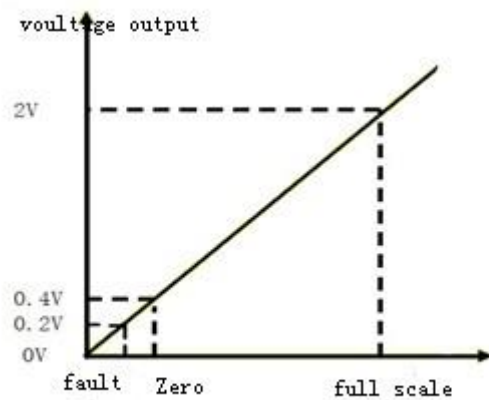
The output value of Vout2 is 0.4-2V, which stands for 0 to full range.

Vin -5V

GND- Power Ground

Vout2-ADC input

After preheating, the value of output voltage from Vout2 represents gas concentration.



### 8.2 PWM output (taking PWM output from 2000ppm as example):

CO2 output range: 0ppm-2000ppm

Cycle: 1004ms  $\pm$  5%

High level output for beginning: 2ms (in name)

Middle of cycle: 1000ms  $\pm$  5%

Low level output for ending: 2ms (in name)

Account formula for CO2 concentration which gets through PWM:

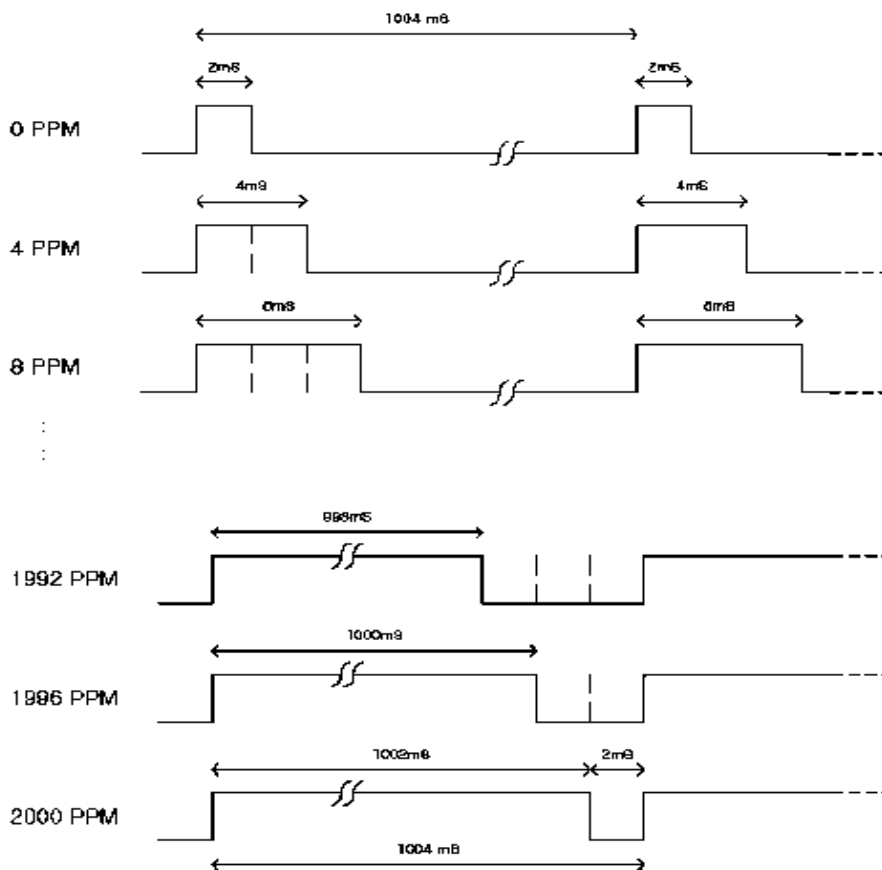
$$C_{ppm} = 2000 \times (T_H - 2ms) / (T_H + T_L - 4ms)$$

Among:

$C_{ppm}$  is calculated CO2 concentration, unit is ppm;

$T_H$  is time for high level during an output cycle;

$T_L$  is time for low level during an output cycle.



### 8.3 Digital connects:

Vin-5V power

GND- Power Ground

RXD connect sensor TXD

TXD connect sensor RXD

You can read gas concentration via Uart, no need to calculate.

### 8.3.1 Communication protocol

#### 1. General Settings

|                |        |
|----------------|--------|
| Baud rate      | 9600   |
| Date byte      | 8 byte |
| Stop byte      | 1byte  |
| Calibrate byte | no     |

#### 2. Command

Each command or return:

Contains 9 bytes (byte 0 ~ 8)

Starting byte fixed 0 XFF

Command contains sensor number (factory default to 0 x01) to check and end

#### Command List:

|      |                             |
|------|-----------------------------|
| 0x86 | Gas concentration           |
| 0x87 | Calibrate zero point (ZERO) |
| 0x88 | Calibrate span point (SPAN) |

#### Read gas concentration

| Send command  |            |         |       |       |       |       |       |             |
|---------------|------------|---------|-------|-------|-------|-------|-------|-------------|
| Byte0         | Byte1      | Byte2   | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte8       |
| Starting byte | Sensor No. | command | -     | -     | -     | -     | -     | Check value |
| 0XFF          | 0x01       | 0x86    | 0x00  | 0x00  | 0x00  | 0x00  | 0x00  | 0x79        |

#### Return value

| Return        |         |                          |                         |       |       |       |       |             |
|---------------|---------|--------------------------|-------------------------|-------|-------|-------|-------|-------------|
| Byte0         | Byte1   | Byte2                    | Byte3                   | Byte4 | Byte5 | Byte6 | Byte7 | Byte8       |
| Starting byte | command | High level concentration | Low level concentration | -     | -     | -     | -     | Check value |
| 0XFF          | 0x86    | 0x02                     | 0x60                    | 0x47  | 0x00  | 0x00  | 0x00  | 0xD1        |

**Gas concentration= high level \*256+low level**

#### Calibrate zero point

| Send command  |            |         |       |       |       |       |       |             |
|---------------|------------|---------|-------|-------|-------|-------|-------|-------------|
| Byte0         | Byte1      | Byte2   | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte8       |
| Starting byte | Sensor No. | command | -     | -     | -     | -     | -     | Check value |
| 0XFF          | 0x01       | 0x87    | 0x00  | 0x00  | 0x00  | 0x00  | 0x00  | 0x78        |

**No return value**

#### Calibrate span point



| Send command  |            |         |                       |                      |       |       |       |             |
|---------------|------------|---------|-----------------------|----------------------|-------|-------|-------|-------------|
| Byte0         | Byte1      | Byte2   | Byte3                 | Byte4                | Byte5 | Byte6 | Byte7 | Byte8       |
| Starting byte | Sensor No. | command | High level span point | Low level span point | -     | -     | -     | Check value |
| 0xFF          | 0x01       | 0x88    | 0x07                  | 0xD0                 | 0x00  | 0x00  | 0x00  | 0xA0        |

**No return value**

### 3. Calibration and calculation

The checksum = (invert (byte 1 +... + 7)) + 1

**Reading gas concentration:**

| Send command  |            |         |       |       |       |       |       |             |
|---------------|------------|---------|-------|-------|-------|-------|-------|-------------|
| Byte0         | Byte1      | Byte2   | Byte3 | Byte4 | Byte5 | Byte6 | Byte7 | Byte8       |
| Starting byte | Sensor No. | command | -     | -     | -     | -     | -     | Check value |
| 0xFF          | 0x01       | 0x86    | 0x00  | 0x00  | 0x00  | 0x00  | 0x00  | 0x79        |

**Except byte 0 , add the other bytes together**

$$0x1 + 0x86 + 0 + 0 + 0 + 0 + 0 = 0x87$$

**Get the value from the first step, and then invert it.**

$$0xff - 0x87 = 0x78$$

**The second value plus one**

$$0x78 + 0x01 = 0x79$$

**Program : C language**

```

char getChecksum(char *packet)
{
    char i, checksum;
    for( i = 1; i < 8; i++)
    {
        checksum += packet[i];
    }
    checksum = 0xff - checksum;
    checksum += 1;
    return checksum;
}

```

## 9. Notes for maintenance

9.1 The sensor should be calibrated regularly. The cycle time is better to be no more than 6 months.

9.2 Do not use the sensor in the high dusty environment for long time.

9.3 Please use the sensor with correct power supply.

9.4 Forbidden to cut the sensor pin.

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