

# Digital Pyroelectric Infrared Sensor (Model: RDA223-F)

# **User's Manual**

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Zhengzhou Winsen Electronics Technology Co., Ltd

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Please keep the manual properly, in order to get help if you have questions during the usage in the future.

Zhengzhou Winsen Electronics Technology CO., LTD.



## **RDA223-F Digital Pyroelectric Infrared Sensor**

Digital PIR sensor RDA223-F, is an integrated design of sensitive element and signal processing chip, packaged sensitive element and IC chip into sensor shield. Sensitive element transfer the human movement signal to high-precision digital chip by differential input for data processing. Then the sensor gives digital signal for easy using.

#### **Features:**

- \* High-precision AD signal process
- \* Differential signal input mode, anti-interference ability
- \* Wide voltage power supply(2.2~5V) and low power consumption
- \* Digital TTL signal output

#### **Applications**

Security product

Human body induction toys

Human body induction lamps, switches and home appliances

Industrial automation control

Smart home

**IOT** terminals

Intelligent appliance



#### **Technical Parameter**

#### 1. Max Limit

Parameter	Symbol	Min	Max	Unit	Note
Supply voltage	V <sub>DD</sub>	0.3	5.5	V	25℃
Output voltage	Vоит	Vss-0.3	V <sub>DD</sub> +0.3	V	25℃
Storage temperature	<b>T</b> st	-40	+125	$^{\circ}$ C	

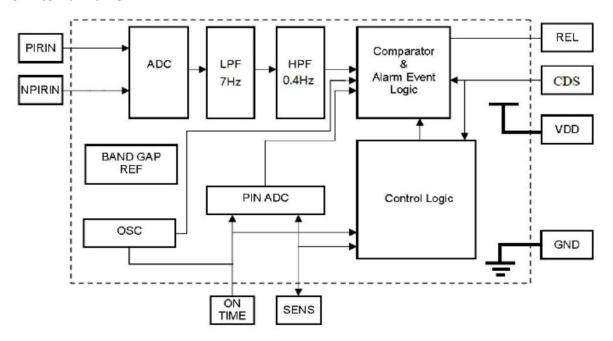
#### 2. Electrical parameter (Unless otherwise specified: T=25 °C, V<sub>DD</sub> =3.0V)

2. Liectifical paramete	<u> </u>	Other Wise s	pecifica. 1-		J-3.017	
Parameter	Symbol	Min	Typical	Max	Unit	Note
Working condition	Working condition					
Voltage	V <sub>DD</sub>	2.2	3.0	5.0	V	Power supply
						mode
Current	IDD	8.0	10	15	uA	V <sub>DD</sub> =3V,
						non-loaded
Temperature	Topr	-20		+70	~	
Output Pin(REL)						
Max output drive	I <sub>REL</sub>			10	mA	V <sub>DD</sub> =5V
current						
REL end outputs high	V <sub>OH</sub>			2.7	V	VDD=3V,IOH=10mA
level						
REL end outputs low	V <sub>OL</sub>	0.3			V	
level						
Block time			2.0		S	
Delay time	ON <sub>TIME</sub>		2.0		S	Non-ajustable

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Oscillators and filters						
Low filter cut-off	F <sub>IPF</sub>			7	Hz	
frequency						
High filter cut-off	F <sub>HPF</sub>	0.4			Hz	
frequency						

#### 3. Internal frame



#### 4. Trigger mode

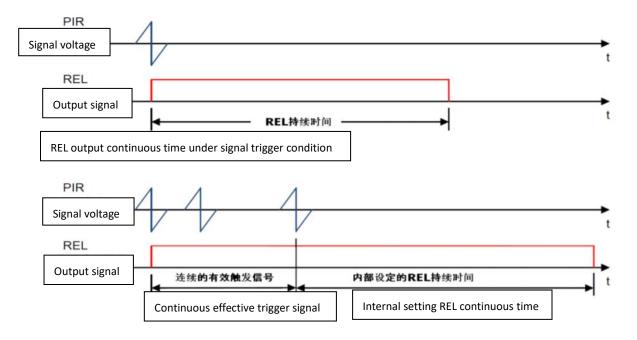
In the normal detection condition, the following two conditions are valid:

- (1) When the signal amplitude successively exceeds the positive and negative thresholds within 4S;
- (2) The signal amplitude exceeds 5 times the threshold;

After the sensor is effectively triggered, the REL pin outputs 2s high level. During the high level output period, if the effective trigger signal is detected again, the output high time is recalculated.

Remark: The sensor has warm-up time. After power on, the REL pin outputs high level for 2 seconds and low level for 2 seconds. Warm-up time has nothing to do with ONTIME

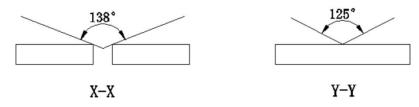




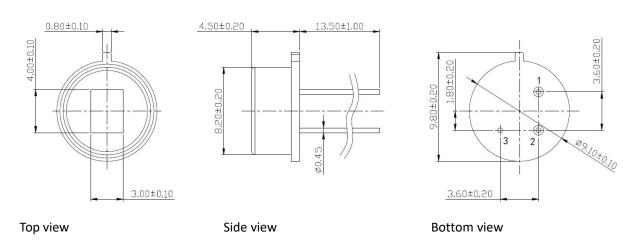
Continuous time of multiple triggering REL output

Note: If the trigger signal is detected again during continuous time, the continuous time will be recalculated.

#### **Sensor Detection Angle**



#### **Component Structure (Unit: mm)**



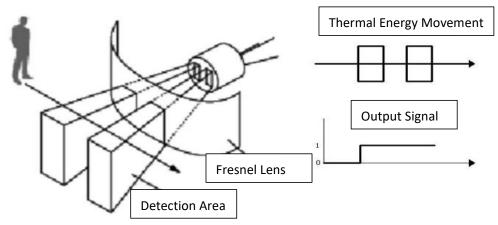
#### **Pin Definition**

Item	Name	Definition
1	VDD	sensor power supply pin
2	REL	sensor output pin, TTL high/low level output, high level output is effective
3	VSS	power ground

#### **Pictures:**



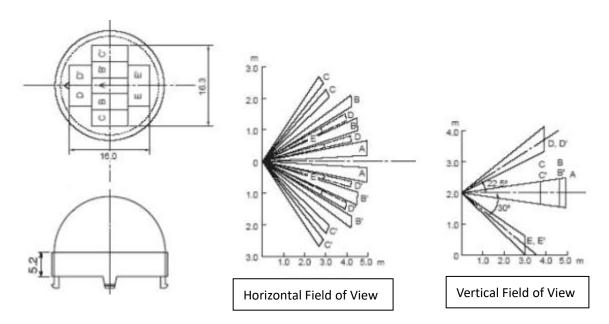
#### Frequency characteristic



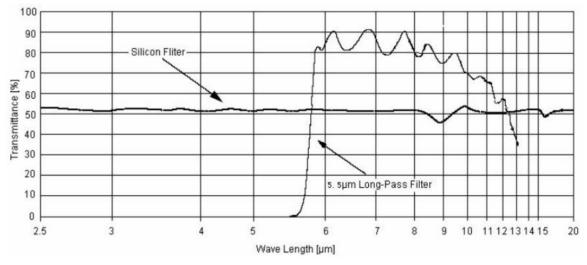
#### **Fresnel Lens:**

Fresnel Lens used, would determine the sensor's detection angle and distance, which can correspond to a variety of detection range and distance, according to customers' requirement.



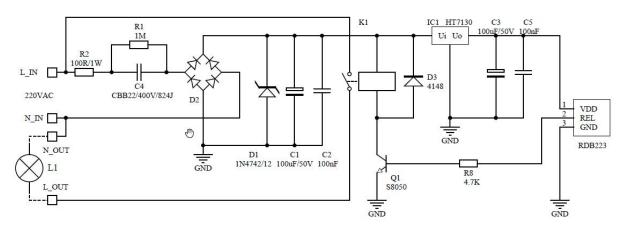


#### **Wave Length**



Note: The graph shows a typical 5~14 um infrared filter reference, and the curve is the average of infrared pass rate. The window material is a special vacuum coating of semiconductor wafers.

### **Typical Application circuit**



RDA223-F Digital Pyroelectric Sensor Typical Reference Circuit

#### **Cautions:**

- 1. The sensor's parameter is obtained by standard testing condition after 1 minute's settling time.
- 2. Please pay attention on Sensor's window direction, must combine with Fresnel lens to get a perfect detecting angle.
- 3. Sensors detecting distance is affected by ambient temperature, moving objects' temperature, Fresnel lens, Amplifier amplification factor, the comparator threshold voltage setting...etc. please take a comprehensive consideration of various parameters when using the sensors.
- 4. Please do not touch the window area to avoid damaging to the optical filter.
- 5. Please handle the sensor with care when using it.
- 6. Please try to use hand soldering and make the soldering time as short as possible. Soldering temperature should be less than 300°C, and soldering time be less than 3 seconds.
- 7. Please get electrostatic protective measures when using this product, as applying static electricity of ±800V or more may damage the sensor.

**Note:** To keep continual product development, we reserve the right to change design features without prior notice.

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