



Laser dust sensor

(Model: ZH07)

Manual

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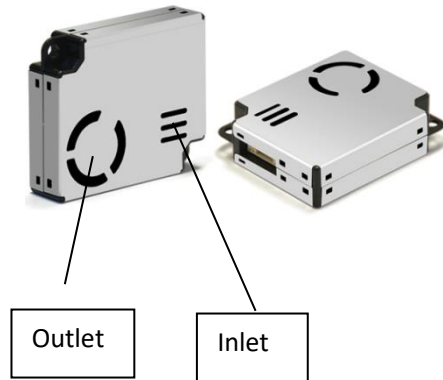
ZH07 Laser dust sensor

Description:

Laser Dust sensor module ZH07 is a common type, small size sensor, using laser scattering principle to detect the dust particles in air, with good consistency and stability. It is easy to use, with UART & PWM output.

Features:

- Good consistency
- Real time response
- Accurate data
- Low power consumption
- Minus resolution of particle diameter 0.3 μm



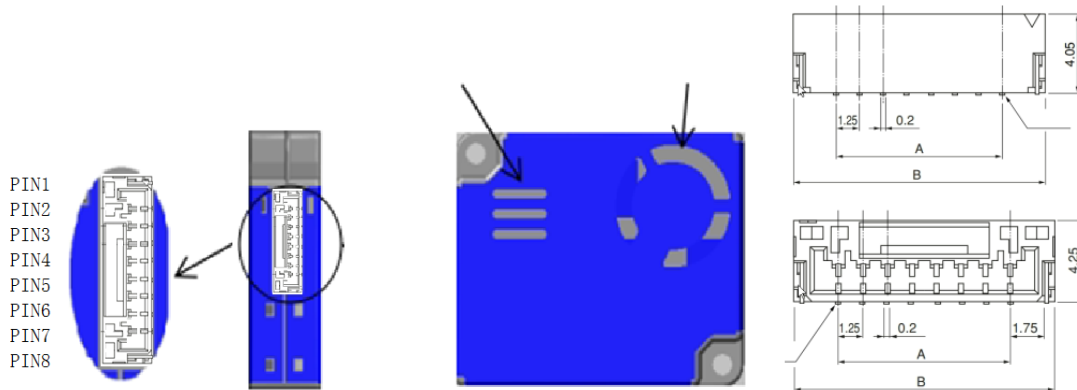
Main Applications

- Air purifiers;
- Ventilation systems;
- Portable instrument;
- Air quality monitoring equipment;
- Air conditioner;
- and smart home fields;

Technical Parameters

Model	ZH07
Detectable particle diameter range	0.3-10μm
Effective Range	0-1000μg/m ³
Detection Interval	1s
PM2.5 Detection Accuracy	0-100 μg/m ³ : ±15μg/m ³ 101-1000 μg/m ³ : ± 15% Reading (Test Condition: 25 ± 2 °C, 50 ± 10% RH, TSI8530, Cigarette, GBT18801-2015)
Preheating Time	30s
Output	UART_TTL Output (3.3V level, default)
	PWM Output (3.3V level, default)
Working Voltage	4.8V ~ 5.5V(DC)
Working Current	< 120mA
Dormancy Current	< 20mA
Response Time	T90 < 30s
Working Humidity	0 ~ 95%RH(No Condensation)
Working Tem.	- 10 ~ 60°C
Storage Tem.	- 30 ~ 70°C
Dimension	48×40×12.5mm(L×W×H)
Weight	< 30g
MTTF	Continuous > 40000H (in clean air)

Pin Order:



Item	Name	Description
PIN1	VDD	DC+5V
PIN2	GND	GND
PIN3	SET	Power-saving mode configuration(low level valid); Suspended or high level (3.3V) normal working
PIN4	RXD	Serial port received (TTL @3.3V)
PIN5	TXD	Serial port transmission (TTL @3.3V)
PIN6	-	Suspended
PIN7	PWM	TTL @3.3V
PIN8	-	NC

Fig 1: pin order

Fig2. Terminal Type (A=7x1.25,B=13.25)

Terminal Description: JST-SM08B-GHS-TB-8P Connector, Pin Spacing 1.25mm, Pin Qty: 8

Communication Protocol

1. Serial communication settings

Baud rate	9600
Date byte	8 bytes
Stop byte	1byte
Check byte	no

Note:

UART protocol Refer to "ZH06 I -IV Laser Dust Sensor User Interface Instructions"

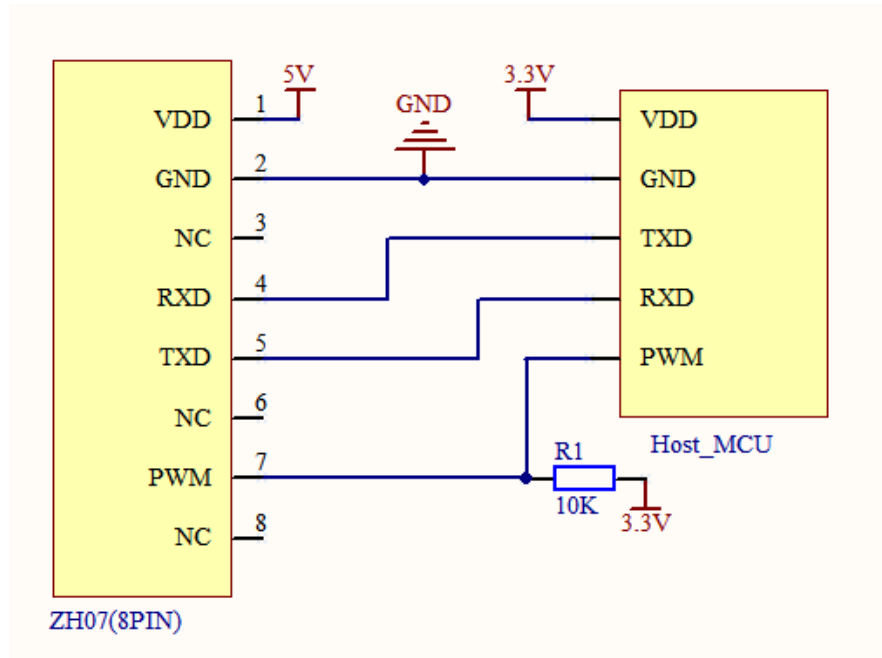
Schematic diagram:

1. Typical circuit (1)

Power supply: 5V; interface level: 3.3V

User MCU working voltage: 3.3V; interface level: 3.3V

The typical interface circuit is as follows:

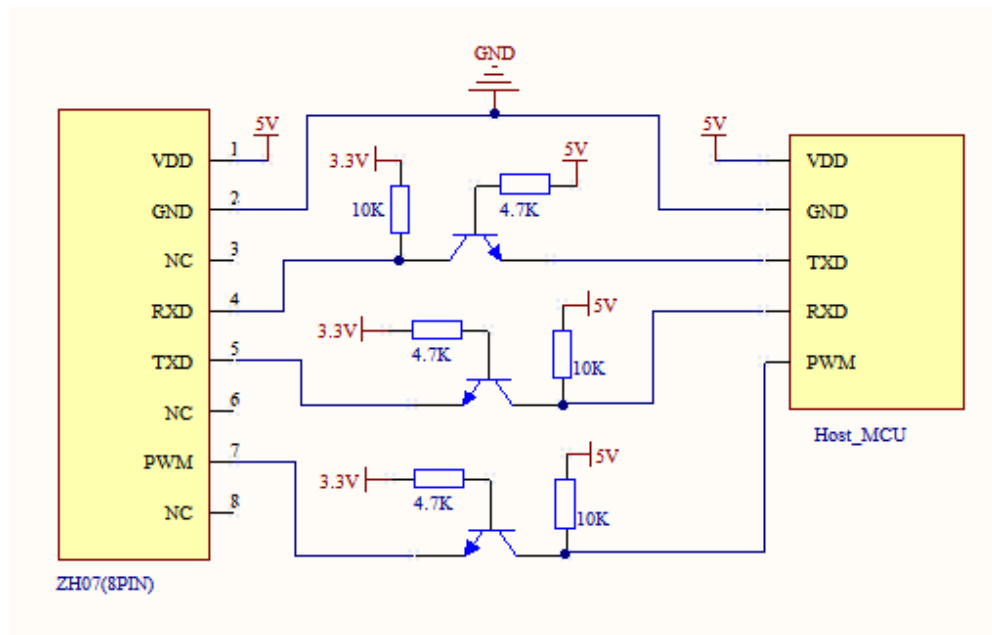


2. Typical circuit (2)

Power supply: 5V; interface level: 3.3V

User MCU working voltage: 5V; interface level: 5V

The typical interface circuit is as follows:



Principle Description:

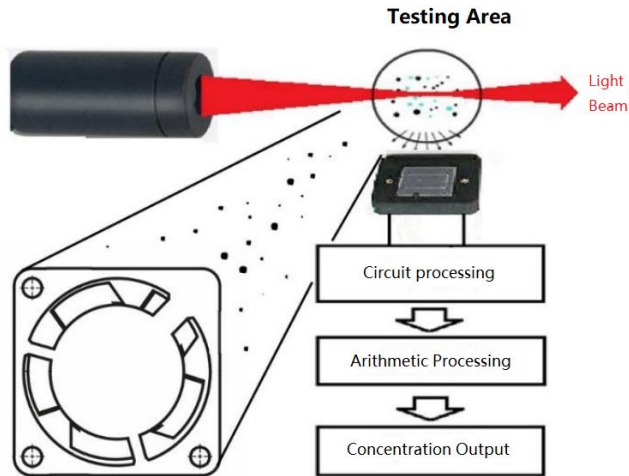


Fig3.Working principle

Sensor construction

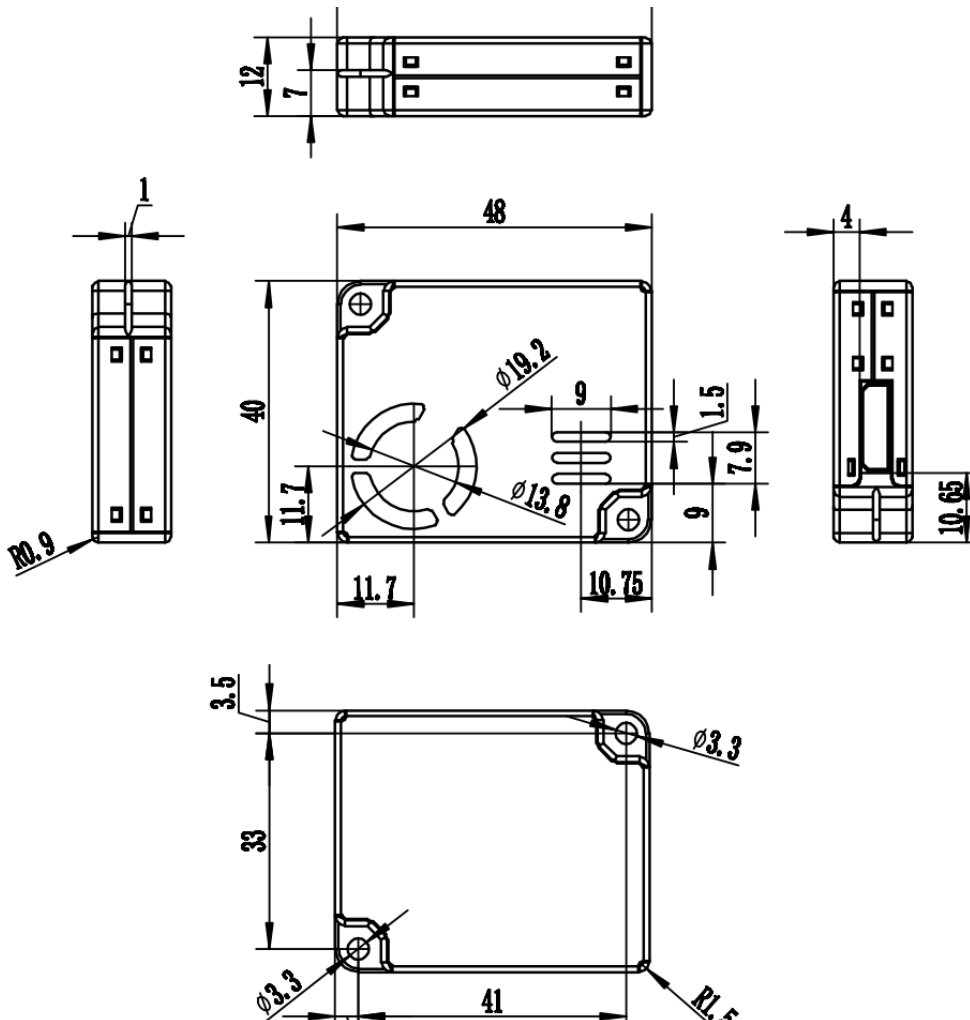
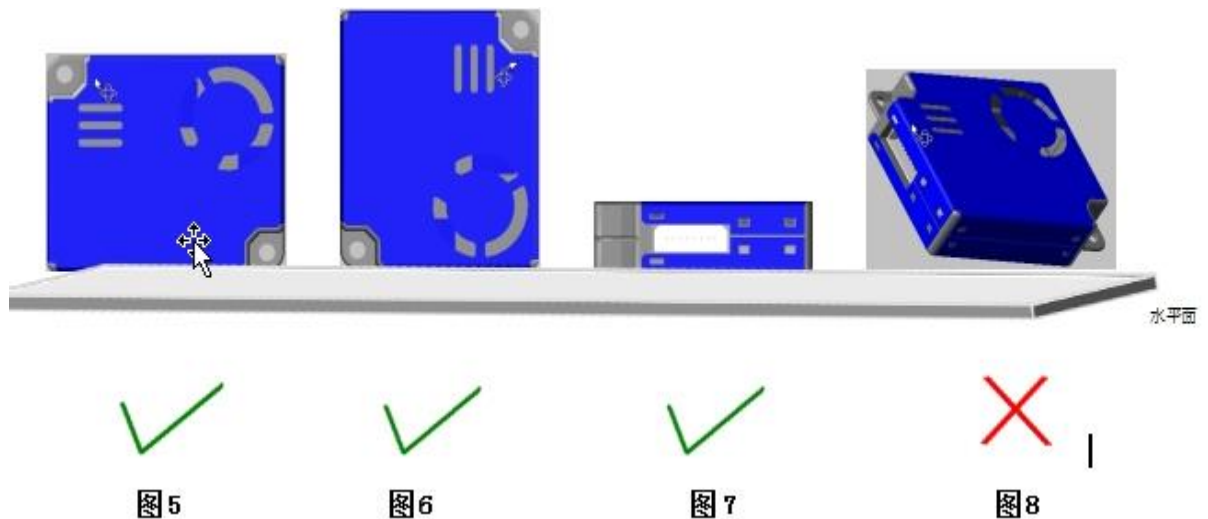


figure 2

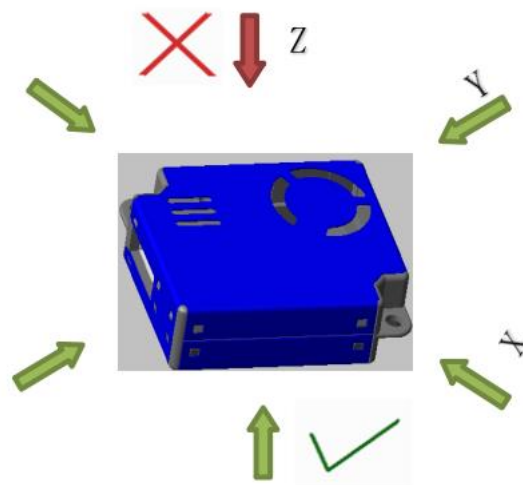
Installation Method:

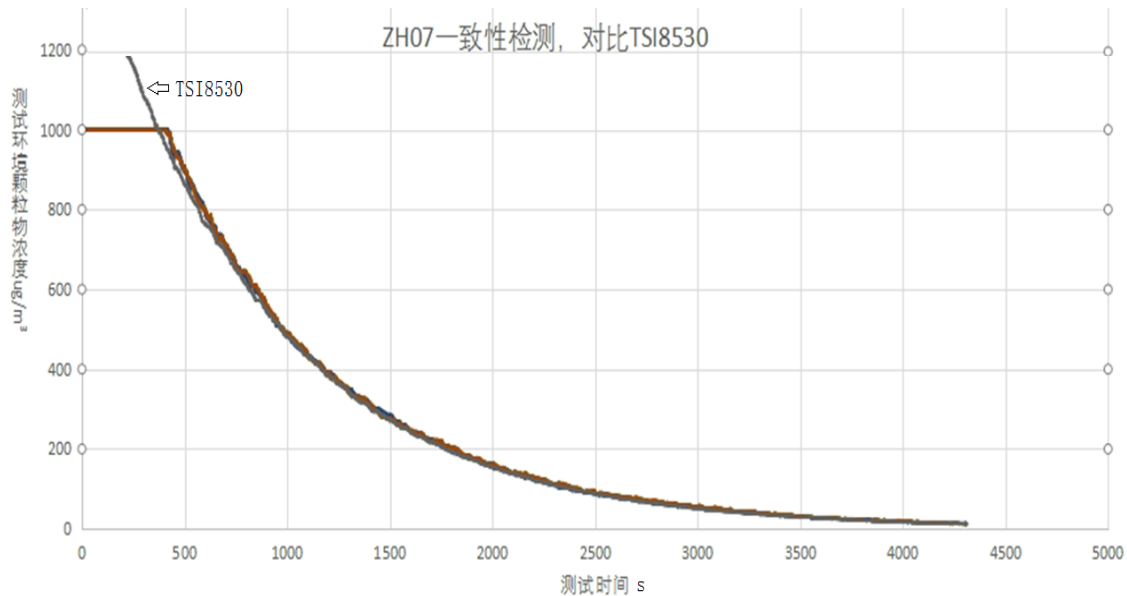
The dust collection hole is the air inlet inside the sensor, which needs to keep good contact with the external air; the fan is installed at the air outlet inside the sensor. When the sensor is installed and working, must avoid strong airflow interference around the sensor; if it cannot be avoided, try to keep the external airflow direction perpendicular to the internal airflow direction of the sensor.

When designing the detection cavity of the whole machine, the effective area of the sampling port of the sensor should be fully considered to ensure the smoothness of the sampling gas path as much as possible. Small sampling area and large air resistance will seriously affect the accuracy of sensor data.



Arrows indicate the airflow perpendicular to the sensor surface



Typical Output Characteristics:**Note:**

The picture shows the data comparison between the conventional ZH07 laser particle sensor and TSI8530 in the test environment.

Abscissa : Testing time related parameters

Ordinate : The concentration of particles in the test environment (with TSI8530 data as reference, unit: $\mu\text{g}/\text{m}^3$).

Note:

1. It is forbidden to remove the shield cover of the sensor and the internal fixing screw of the sensor, because the shield cover of the sensor is connected with the internal power supply of the sensor through the internal spring. If the shield cover of the sensor is removed, the anti-interference ability of the sensor will be poor, the output value of the sensor will change, and the performance of the sensor will be poor. In addition, and please pay attention to the metal shield of the sensor, avoid contact with other external circuits or conductive parts, so as to reduce the impact of external interference on the sensor.

2. Excessive impact or vibration will affect the accuracy and life of the sensor detection value, so the sensor should avoid falling or vibration when installing and using.

3. This sensor is suitable for the detection of dust particles in the ordinary indoor environment.

The actual working environment should try to avoid oil&smoke environment, too large dust

particles, high humidity environment, such as: kitchen, bathroom, smoking room, outdoor environment, etc. If it is used in such environments, corresponding protective measures shall be added to the user's equipment to prevent viscous particles or large particles from entering the interior of the sensor and forming accumulation in the interior of the sensor which will affect the performance of the sensor. (for example, in the working environment with floccules or fibers, the corresponding coarse filter net should be added ahead the air inlet of the sensor to avoid floccules or large sundries from entering the sensor and blocking the light path of the sensor, thus affecting the detection accuracy of the sensor.)

4. The fan is the air outlet, and the dust collection hole is the air inlet. During the using of the sensor, the sensor should not be directly placed inside the air duct of the purifier. If it cannot be avoided, an independent space structure should be set up for the installation position of the sensor. The air flow direction is as shown in 'Installation Method'. The sensor should not be impacted by the air flow in the direction of the red arrow. There should be no obstructions within 2cm around the outlet of the fan. In this independent space, it should be avoided that the air flow from the outlet directly flows back to the inlet, which will affect the accuracy of detection.

5. Under normal working condition of normal temperature&pressure, the key component of the sensor-laser, can work continuously for more than 40000 hours, and the life of the sensor can be greatly prolonged by setting the sensor's sleep mode and interval working time. The maximum cumulative life of the sensor can be more than 5 years. Please refer to the user interface instructions for detailed operation methods, or you can contact our technical service staff by telephone or email.

6. The sensor data mentioned in this manual is about to ensure the consistency of the sensors we produced, the comparison standard will not refer to any third-party testing instruments or data . If the user wants the final detection results to be consistent with the third-party testing instrument, the user can do data fitting correction according to the actual detection results.

Packing:

1. Put the sensor into the Pearl Foam Tray as shown in the picture below.
2. Put the whole plate of sensors in Small Box one by one, then puts a foam plate at the top.

Each Small Box can hold 25 sensors.

3. Select the appropriate carton according to the quantity of the order:

Carton F: 355 x 310 x 285mm, can hold 200 sensors, total weight around 6.2kg.

Carton D: 630 x 280 x 405mm, can hold 600 sensors, total weight around 18.0kg.

Note: Please pay attention to water proof of the carton during transportation

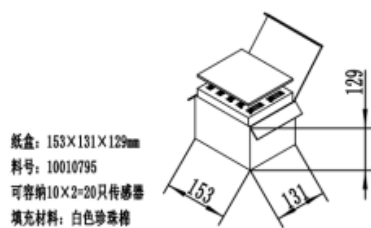


图 11-小盒

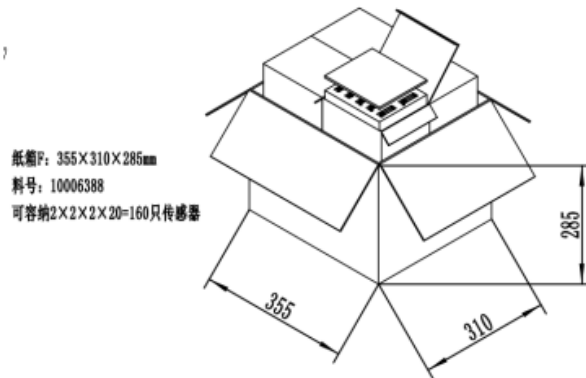


图 12-纸箱 F

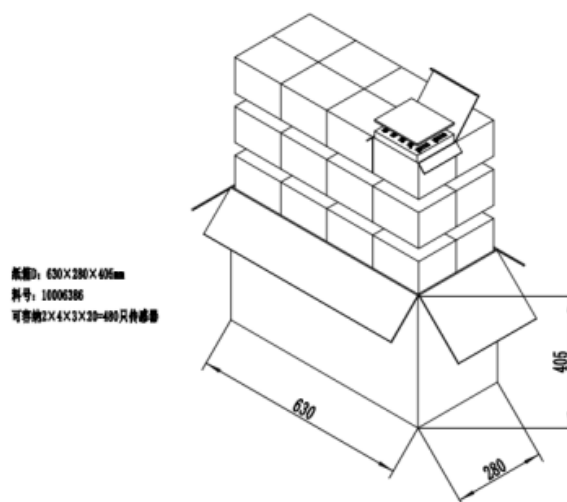


图 13-纸箱 D

Reliability Testing:

	Testing Item	Testing Condition	Decision Criteria	Number of Tests - n Number of Failures - c
1	Zero output range	The test cabin meets the requirements of clean air: the mass concentration of dust is not more than $5.0 \mu\text{g} / \text{m}^3$, the sensor is powered on, and the output value is recorded six times.	Zero point output range: < $15\mu\text{g}/\text{m}^3$	n=28 c=0
2	Uniformity	Record the output value of the sensor for 6 times at each concentration of 50, 130 and $260\mu\text{g}/\text{m}^3$, totally 18 times, take the maximum value respectively	Meet the description of "PM2.5 detection accuracy"	n=28 c=0
3	stability	The sensor is continuously powered on for 15d, Measure the output range and relative error of zero point.	Zero point output range: < $15\mu\text{g}/\text{m}^3$ Relative error $\pm 15\%$	n=2 c=0
4	response time	When the output value of the sensor reaches $450 \mu\text{g} / \text{m}^3$ for the first time, record the time T1 at this time. Calculate the response time $T90 = t1-t0$, repeat the measurement 3 times and take the average value	response time: $T90 < 45\text{s}$	n=2 c=0
5	High Concentration Inundation	The sensor is powered on for 10min under the environment of $2000 \mu\text{g}/\text{m}^3$. Measure the output range of zero point and relative error after completion.	Zero point output range: < $15\mu\text{g}/\text{m}^3$ Relative error $\pm 15\%$	n=2 c=0
6	Power on/off	Keep the voltage $\text{dc}5 \pm 0.1\text{V}$ for 5min; keep the power off for 5min and circulate for 24h. Measure the output range of zero point and relative error after completion.	Zero point output range: < $15\mu\text{g}/\text{m}^3$ Relative error $\pm 15\%$	n=2 c=0
7	Noise	The background noise is less than 30dB (a), the sensor works stably for 20min, and the sound level meter is placed on the same horizontal plane 0.8m high from the ground. The distance between the two is 1m. Each measurement is conducted three times, and the maximum value is taken	Working noise: $\leq 40\text{dB}$ (a)	n=2 c=0
8	Low Temperature Storage	The sensor is not powered on, under the environment condition of $-30 \pm 2 \text{ }^\circ\text{C}$, the duration is 16h, and stable at room temperature for 2h. Measure the output range of zero point and relative error after completion.	There shall be no obvious dents, scratches, cracks, deformation and other defects on the sensor surface, no bubbles, crazing and falling off on	n=2 c=0

9	High Temperature Storage	The sensor is not powered on, under the environment of $70 \pm 2 \text{ }^\circ\text{C}$, the duration is 16h, and stable at room temperature for 2h. Measure the zero point output range and relative error after completion	the coating and coating, no loosening and falling off on the connectors and parts, no rust and mechanical damage on the metal components. Zero point output range: $< 15\mu\text{g}/\text{m}^3$ Relative error: $\pm 15\%$	n=2 c=0
10	High Temperature Work	The sensor is powered on and operated under $50 \pm 2 \text{ }^\circ\text{C}$ environmental conditions for 2h, Measure the zero output range after completion.	There shall be no obvious dents, scratches, cracks, deformation and other defects on the sensor surface, no bubbles, crazing and falling off on the coating and coating, no loosening and falling off on the connectors and parts, no rust and mechanical damage on the metal components. Zero point output range: $< 15\mu\text{g}/\text{m}^3$	n=2 c=0
11	Low Temperature Work	The sensor is powered on and operated under the ambient condition of $-10 \pm 2 \text{ }^\circ\text{C}$, lasting for 2h, Measure zero point output range after completion		n=2 c=0
12	Vibration Test	The sensor is not packed and powered off. Frequency range: (10-150) Hz; Sine amplitude: 1.5mm; Frequency range: 1oct; X, y, Z three axes, each sweeping 15 times. Measure the output range of zero point and relative error after completion.	There shall be no obvious dents, scratches, cracks, deformation and other defects on the sensor surface, no bubbles, crazing and falling off on the coating and coating, no loosening and falling off on the connectors and parts, no rust and mechanical damage on the metal components. Zero point output range: $< 15\mu\text{g}/\text{m}^3$	n=2 c=0
13	Drop Test	The packaged sensor, with a height of 1m, falls on a surface of concrete or a smooth and hard rigid surface. Each of the six different faces falls freely once. Measure the output range of zero point and relative error after completion.		n=2 c=0
14	Electrostatic Interference	When the sensor is electrified, the surface of 2000V metal shell is discharged 8 times, and the ground plate is discharged 2 times at 10cm around the sample. The time interval of each discharge is at least 1s. Measure the output range of zero point and relative error after completion.	Zero point output range: $< 15\mu\text{g}/\text{m}^3$ Relative error: $\pm 15\%$	n=2 c=0