



# Particles Sensor

(Model: ZPH01B)

# Manual

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Zhengzhou Winsen Electronics Technology Co., Ltd

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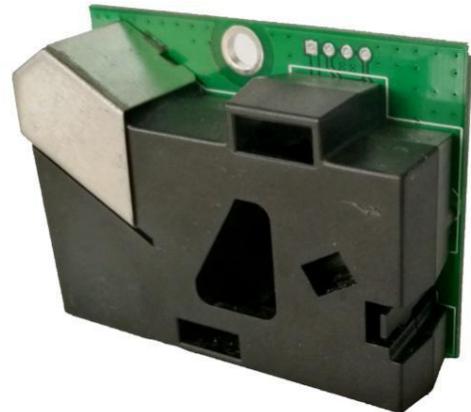
Zhengzhou Winsen Electronics Technology CO., LTD

## Particles Sensor

### Profile

This sensor adopts advanced PM2.5 detection technology to detect PM2.5. PM2.5 detection adopts particle counting principle to detect the particles (diameter  $\geq 1\mu\text{m}$ ).

Before delivery, the sensor has been aged, debugged, calibrated and has good consistency and high sensitivity.



### Features

- Good long-term stability
- High sensitivity
- Rich interface output methods
- Good consistency
- Easy to install and maintain

### Applications

- Air purifier
- Air refresher
- Portable meter
- Air ventilating device
- Air conditioner
- smoke alarm &etc.

### Technical Parameters **Stable.1**

|   |         |  |
|---|---------|--|
| Model                                   |         | ZPH01B   |
| Working voltage range                   |         | $5 \pm 0.2$ V DC                                 |
| Output                                  |         | PWM /UART  |
| Output Voltage                          |         | $5 \pm 0.2$ V DC                                 |
| Detection ability for minimum particles |         | 1 $\mu\text{m}$ diameter                         |
| Warm-up time                            |         | $\leq 1$ min                                     |
| Response time                           |         | $\leq 5$ s                                       |
| Humidity range                          | Storage | $\leq 95\%$ RH                                   |
|   | Working | $\leq 95\%$ RH                                   |
| Temperature range                       | Storage | $-30^{\circ}\text{C} \sim 50^{\circ}\text{C}$    |
|   | Working | $0^{\circ}\text{C} \sim 50^{\circ}\text{C}$      |
| Size                                    |         | $59.5 \times 44.5 \times 20\text{mm}$<br>(LxWxH) |
| Physical interface                      |         | EH2.54-5P terminal socket                        |

### Basic dimensions

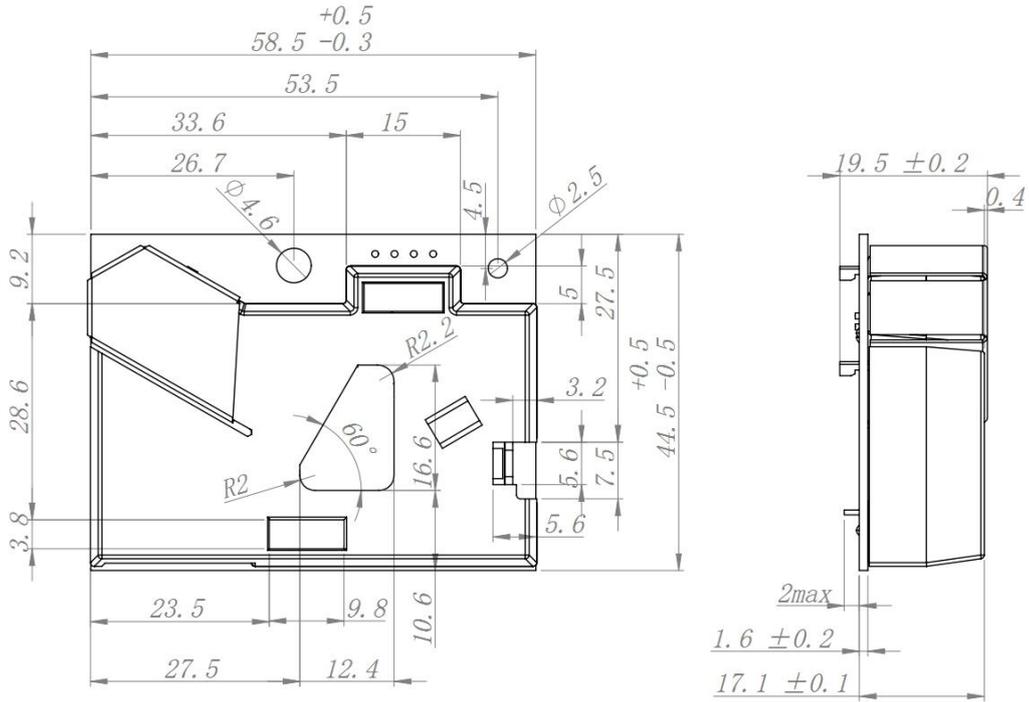


Fig1.Structure

### Detection Principle

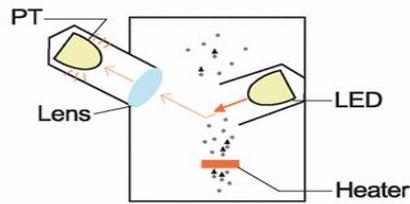
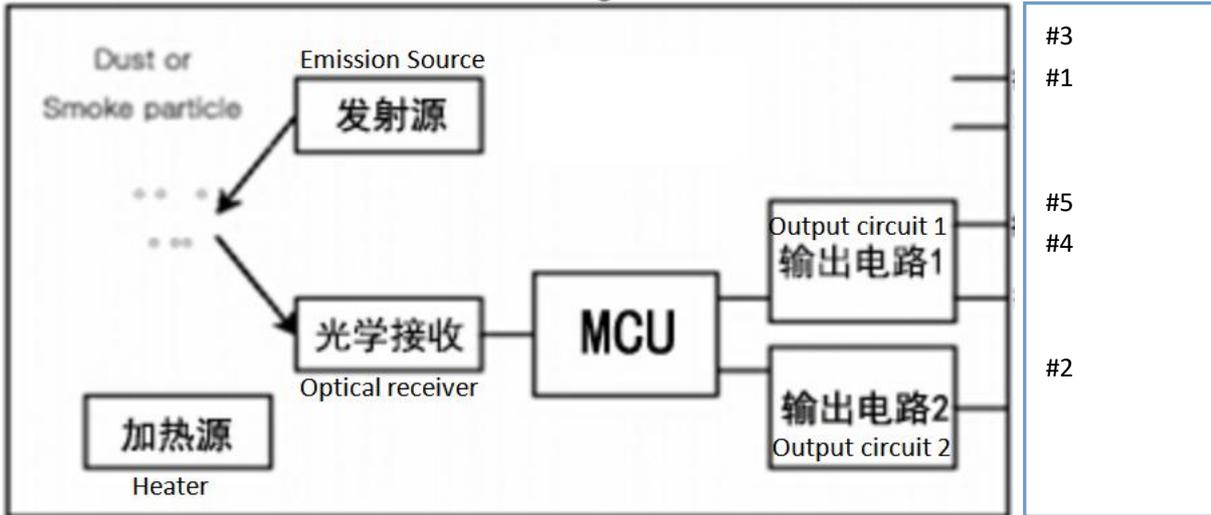


Fig 2. Principle schematic 1



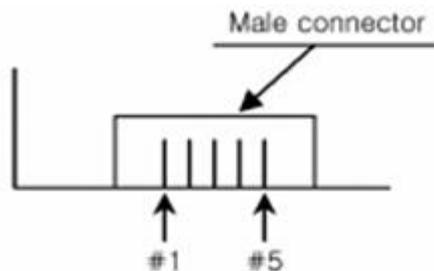
**Fig 3.Principle schematic 2**

**Remarks**

The ZPH01B dust sensor uses a power resistor to heat the air, and the rising of the hot air drives the ambient gas (PM2.5) into the detection light path to perform detection. The optical structure determines that the installation and placement of the sensor have certain specifications, otherwise it will cause abnormal detection data.

**Pins Definition Stable2.**

| Pin  | PWM model                                    | UART model |
|------|--|------------|
| PIN1 | Control pin(refer the detailed instructions) | <b>GND</b> |
| PIN2 | Output PM2.5                                 | NC         |
| PIN3 | VCC  | VCC        |
| PIN4 | NC   | TXD        |
| PIN5 | GND  | GND        |



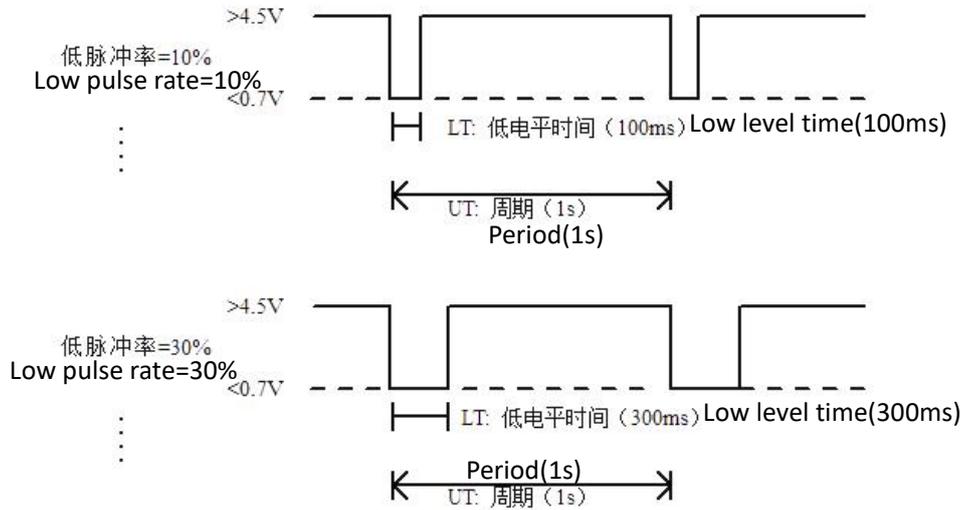
**Fig4: Pins sketch**

**Remarks**

The two modes of ZPH01B can only be set before the sensor is normally energized. Please make the hardware connection in advance. Pin1 can only be used as a signal input control pin in UART

mode, and does not assume the GND function of the module's power supply. Otherwise, a power failure will cause irreparable damage to the module.

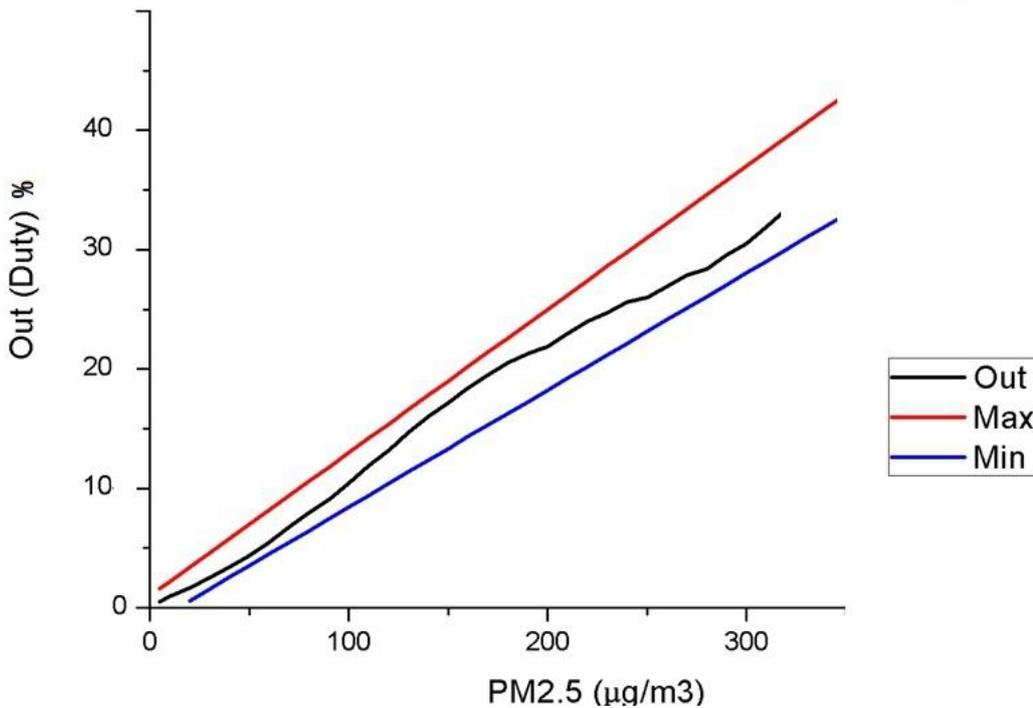
**PM2.5 output wave in PWM mode**



**Fig5.PM2.5 output wave in PWM mode**

- NOTE: 1.LT is the pulse width of low level in one period.  
 2.UT is the pulse width of one period.  
 3.Low pulse rate RT:  $RT = LT / UT \times 100\%$

**The relationship between low pulse rate of output and particles number**



**Fig6.The relationship of low pulse rate of output and particles number**

NOTE: People usually use different levels (best,good,bad,worst) to describe the air quality condition.

**Recommended plan:**

Best: 0.00%-4.00%

Good: 4.00%-8.00%

Bad: 8.00%-12.00%

Worst: >12.00%

**Communication protocol**

**1.General Settings**

**Stable 3.**

|                 |               |
|-----------------|---------------|
| Baud rate       | 9600          |
| Interface level | 5±0.2 V (TTL) |
| Data bit        | 8byte         |
| Stope bit       | 1byte         |
| Check byte      | no            |

**2.Communication command**

Module sends the concentration value every other one second. Only send,no receive. Command as follow:

| 0          | 1                        | 2                     | 3                              | 4                               | 5           | 6    | 7           | 8           |
|------------|--------------------------|-----------------------|--------------------------------|---------------------------------|-------------|------|-------------|-------------|
| Start byte | Detection type name code | Unit (Low pulse rate) | Integer part of low pulse rate | Decimals part of low pulse rate | Reservation | Mode | Reservation | Check value |
| 0XFF       | 0X18                     | 0X00                  | 0x00-0x63                      | 0x00-0x63                       | 0x00        | 0x01 | 0x00        | 0x00-0xFF   |

**Stable 4.**

**Note:**

1. Conversion of duty cycle: Example:

In a frame of normal data sent by the sensor, the third bit is 0X12 and the fourth bit is 0X13. It means: the duty cycle of the sensor output is 18.19%.

2. Conversion of PM2.5:

The detected environmental PM2.5 concentration can be obtained by converting the proportional coefficient  $k * 18.19\%$ . Take 1000 according to the empirical coefficient  $k$ .

### 3. Check and calculation

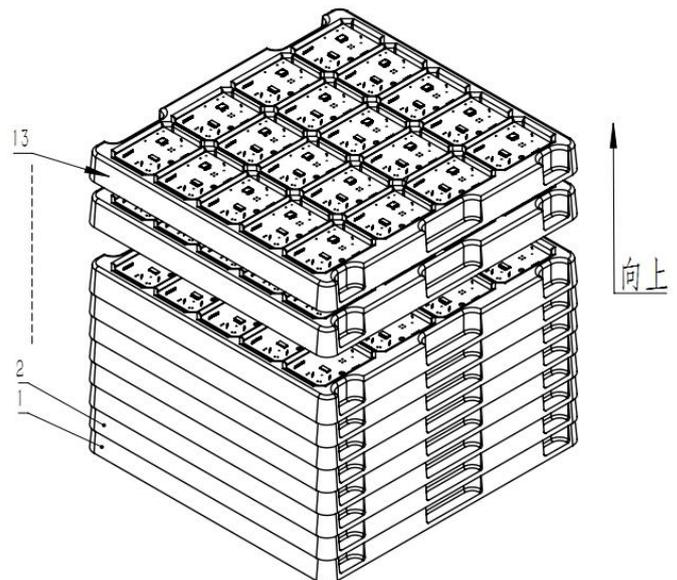
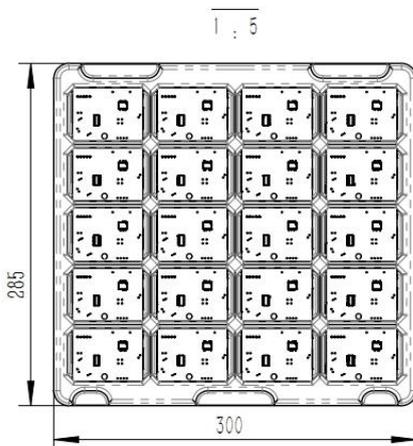
```

/*****
* Funtion name: ucharFucCheckSum(uchar *i,uchar ln)
* Funtion description:Sum check(Negate the sum of send and receive protocol 1/2/3/4/5/6/7
and +1 )
*****/
unsigned char FucCheckSum(unsigned char *i,unsigned char ln)
{
    unsigned char j,tempq=0;
    i+=1;
    for(j=0;j<(ln-2);j++)
    {
        tempq+=*i;
        i++;
    }
    tempq=(~tempq)+1;
    return(tempq);
}

```

### Packing

1. Put the dust sensor in the blister tray in the same direction.
2. According to the specifications of the packing box, place the blister tray with the sensor in the corresponding number of layers.
3. Put the packed sensor into the carton.
4. The carton is sealed and packed.
5. Orders with a single shipment quantity less than the smallest box are not limited to this specification.



每个吸塑托盘容纳4\*5=20支模组

Figure 7 The blister tray contains the sensor

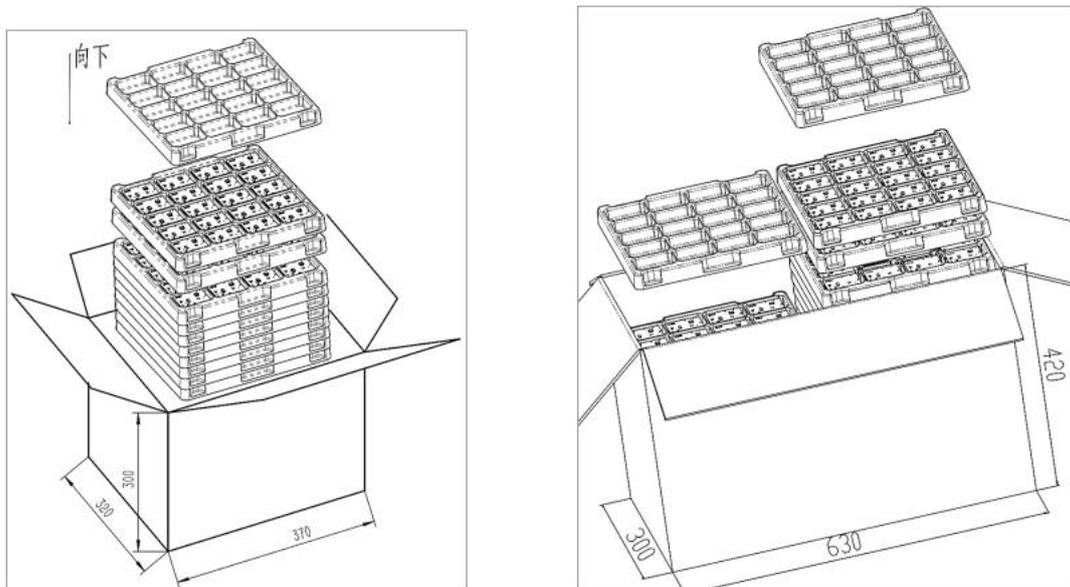


Figure 8 Different specifications of packaging boxes contain sensors

Carton size:

Packing box 1: 355 × 310 × 285mm, 20 × 13 = 260 sensors can be installed.

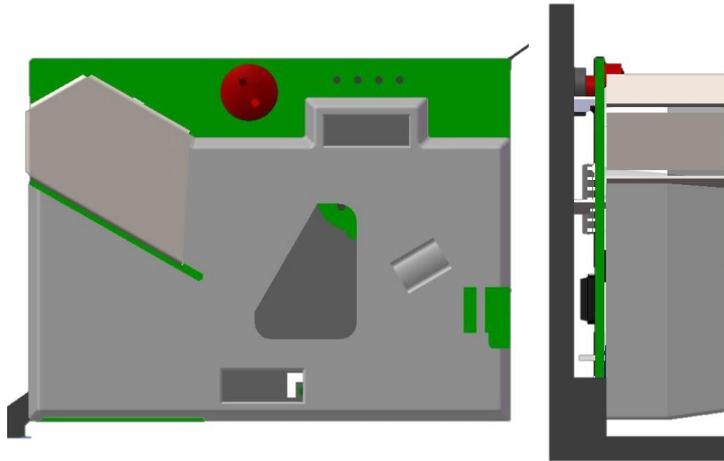
Packing box 2: 630 × 280 × 405mm, can fit 20 × 2 × 19 = 760 sensors

## Matters needing attention when using the sensor

### Terms of Use

1. Installation requirements: The sensor is installed vertically to ensure a smooth detection gas path and avoid contact with organic solvents.

1.1 Must be installed vertically. The sensor as a whole must be fixed and installed perpendicular to the horizontal plane. As shown in Figure 3, the power resistor heats the air, and the rising of the hot air drives the outside air into the optical path and removes it in time. The wrong installation method will make the sensor reading abnormal.



1.2 Ensure a smooth detection air path. The external air flow can enter the optical cavity of the sensor smoothly and be discharged in time. When applied to an air cleaner, the air flow of the fan cannot affect the stability of the air path detected by the sensor, and it can be installed on one side of the body.

1.3 Avoid light The dust sensor uses a specific wavelength light LED and a photoelectric sensor with visible light to detect dust particles. The external light radiation will affect the optical signal of the dust sensor. It is recommended to use a sponge to cover the center triangle hole of the dust sensor (as shown in Figure 1). Block the air inlet and outlet of the sensor.

2. Power supply requirements: The metal shield of the module is connected to the circuit GND. The GND pin should be prevented from being connected to the system with a voltage higher than the safety voltage of the human body. Do not apply to the system involving personal safety

3. Cleaning the lens: The lens needs to be cleaned regularly according to the usage environment, about once every 6 months. When cleaning, use one end of a cotton swab with clean water to gently wipe the surface of the lens, and then use the other end to wipe off water stains in time. Do not wipe the lens with organic solvents such as alcohol.

## Avoid bad interference

Avoid contact with water vapor. Keep away from the bathroom or air humidifier. Water mist will cause abnormal fluctuations in PM2.5 data; splashing or immersing in water will cause the sensor's sensitivity to decrease.

## Transport storage

1. Avoid vibration. Frequent and excessive vibration during transportation and assembly will cause misalignment of optoelectronic devices and affect the original calibration data.

2. Long-term storage Store in a sealed bag to avoid contact with corrosive gases to damage the circuit board and optical devices

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